

# Random databases and $\epsilon$ -entropy

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## Outline:

1. Introduction. Basic notation.
2. Probabilistic models for databases.
3. Rényi  $\epsilon$ -entropy.
4. Tests in random databases.
5. Summary.

## Basic notation

**Database** ( $m \times n$ -table) of  $m$  **tuples** (or records) with  $n$  **attributes** (or features),  $U := \{1, \dots, n\}$

$$R = \begin{pmatrix} t_1(1) & \cdots & t_1(n) \\ \cdots & \cdots & \cdots \\ t_m(1) & \cdots & t_m(n) \end{pmatrix}$$

Tuples  $t_j(U) = (t_j(1), \dots, t_j(n))$ ,  $j = 1, \dots, m$ , are vectors with values in  $D = D_1 \times \dots \times D_n$ , where  $D_i$  are **domains**  $i = 1, \dots, n$ .

A set of attributes  $A$  is called a **test** in  $R$  if all tuples  $t_A(i)$ ,  $i = 1, \dots, m$ , are different.

We say that vectors  $x$  and  $y$  in a metric space  $(S, d)$  are  $\epsilon$ -**close**,  $\epsilon \geq 0$ , if the distance  $d(x, y) \leq \epsilon$ . A set of attributes  $A$  will be called a  $\epsilon$ -**test** if there are no  $\epsilon$ -close tuples  $t_A(i), i = 1, \dots, m$ . Let  $N_\epsilon(A) := \#\{\epsilon\text{-close tuples in } R_A\}$ .

### Example

$$R = \begin{pmatrix} 1 & 1 & 0 & 0 & 0 \\ 0 & 0 & 1 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1 \end{pmatrix}$$

- tests :  $\{2, 3\}, \dots$
- not a test :  $\{1, 4\}$
- $\epsilon$ -test,  $\epsilon = 0.5$ ,  $\{3, 5\}$  but not a 1.0-test for the Euclidian norm.

## Database problems:

- Data search optimization; Tests and minimal tests.
- Database design; constraints sets complexity.

### Problems:

- Probabilistic models for discrete and continuous databases;
- The distribution of the number of  $\epsilon$ -coincidences  $N_\epsilon(A)$
- Joining multiple tables with approximate matching.

**The worst case setting** approach:

Combinatorial or deterministic methods; restrictive class of models and overestimating complexity.

**Average case setting** approach:

Probabilistic methods; general class of models; *where* the distribution of tests concentrates (i.e., *typical* tests), and *for which* model parameters.

### **Probabilistic models for databases.**

1. Tuples  $t_j(U) \in \prod_{i \in U} D_i, j = 1, \dots, m$ , are independent random vectors;
2.  $\mathcal{P}$  is a common (discrete or continuous) distribution for tuples

# Examples

**Uniform** random database if  $\mathcal{P}$  is a uniform (discrete or continuous) distribution  $\mathcal{U}$  in  $D$ .

**Gaussian** database if  $\mathcal{P}$  is a Gaussian distribution  $\mathcal{G}$  in  $D = \mathbb{R}^n$ .

(Generalized) **Bernoulli** random database if all attributes are iid random  $Q$ -variables.

For instance, the conventional Bernoulli model corresponds to a binary one for the discrete Bernoulli distribution with  $D_i = \{0, 1\}$  for all attributes.



## Measures of uncertainty

**Shannon** For a discrete distribution  $\mathcal{P} = \{p(\mathbf{k}), \mathbf{k} \in D\}$ ,

$$h_1(\mathcal{P}) := - \sum_{\mathbf{k}} p(\mathbf{k}) \log_2 p(\mathbf{k})$$

**Rényi** For a discrete distribution  $\mathcal{P} = \{p(\mathbf{k}), \mathbf{k} \in D\}$ ,

$$h_s(\mathcal{P}) := \frac{1}{1-s} \log_2 \left( \sum_{\mathbf{k}} p(\mathbf{k})^s \right), \quad s \neq 1,$$

and  $h_s(\mathcal{P}_A) \rightarrow h_1(\mathcal{P}_A)$  as  $s \rightarrow 1$ .

**Rényi** for a continuous random variable  $X$ , **differential entropy**. The uniform quantizer  $q(X) = [NX]/N$ . Then for  $p_k := P\{q(X) = k/N\} = P\{k/N < X \leq (k+1)/N\}$

$$h_\epsilon^R(X) := -\log_2 \sum_k p_k^2, \quad \epsilon = 1/N, s = 2$$

$$h_\epsilon^R(X) = \log_2 \frac{1}{\epsilon} - \log_2 \int_R p(x)^2 dx + o(1),$$

with a straightforward generalization to the vector case  $R^n$  and the general class of entropies

$$h_\epsilon^R(X) = n \log_2 \frac{1}{\epsilon} - \log_2 \int_{R^n} p(x)^2 dx + o(1).$$

**Kolmogorov** For a metric space  $(S, d)$  and  $N_\epsilon(S, d)$  the cardinality of the minimal  $\epsilon$ -net

$$H_\epsilon(S) = \log_2 N_\epsilon(S, d).$$

**Kolmogorov-Shannon** For random continuous variables  $X, Y$  with the mutual information

$$I(X, Y) = \int p(x, y) \log \frac{p(x, y)}{p(x)q(y)} dx dy,$$

the **risk distortion** (or  $\epsilon$ -entropy)

$$R_\epsilon(X) = \inf \{ I(X, Y) : E\|X - Y\|^2 \leq \epsilon^2 \}.$$

**Posner-Rodemich** For a probabilistic separable metric space  $(S, d, \mu)$  and a countable  $\epsilon$ -partition  $\pi_\epsilon = \{A_i\}$  with diameter  $d(A_i) \leq \epsilon$ ,

$$H_\epsilon^{PR}(S, \mu) = \inf_{\pi_\epsilon} \sum \mu(A_i) \log_2(1/\mu(A_i))$$

There are  $\epsilon, \delta$ -variants for Kolmogorov and Posner-Rodemich when defined on  $S \setminus B$  and  $\mu(B) < \delta$ .

**Haussler and Opper** (the volume-scaling entropy). For a probabilistic separable metric space  $(S, d, \mu)$ ,  $X$  is a random  $\mu$ -vector,

$$H_\epsilon^{HO}(S, \mu) = \mathbf{E} \log_2(1/\mu(B_\epsilon(X)))$$

## The Rényi $\epsilon$ -entropy (cf. Szpankowski for discrete sequences)

Let  $X, Y$  be independent  $\mathcal{P}$ -distributed random vectors with values a metric space  $(S, d)$  and  $B_\epsilon(x) := \{y : d(x, y) \leq \epsilon\}$  be a  $\epsilon$ -ball, the  $\epsilon$ -ball probability  $p_\epsilon(x) := P\{Y \in B_\epsilon(x)\}$ . The generalized Rényi  $\epsilon$ -entropy

$$h_{2,\epsilon}(\mathcal{P}) := -\log_2 P\{d(X, Y) \leq \epsilon\} = -\log_2 p_\epsilon(X).$$

In the general case,

$$h_{s,\epsilon}(\mathcal{P}_A) := \frac{1}{1-s} \log_2 \mathbf{E} p_\epsilon(X)^{s-1}, s \neq 1,$$

the generalized Shannon  $\epsilon$ -entropy as  $s \rightarrow 1$ ,

$$h_{1,\epsilon}(\mathcal{P}) := -\mathbf{E} \log_2 p_\epsilon(X).$$

(cf. the volume-scaling entropy).

**Proposition.** *Let  $X = (X_A, X_B)$  be a random  $\mathcal{P}$ -vector.*

*(i)  $h_{2,\epsilon}(\mathcal{P}) \geq 0$ . If  $h_{2,\epsilon}(\mathcal{P}) = 0$ , then for some  $x_0$ ,  $P\{X \in B_\epsilon(x_0)\} = 1$ . On the other hand, if  $P\{X \in B_\epsilon(x_0)\} = 1$ , then  $h_{2,2\epsilon}(\mathcal{P}) = 0$ ;*

*(ii)  $h_{2,\epsilon}(\mathcal{P}_A) \leq h_{2,\epsilon}(\mathcal{P}_{A \cup B})$ ;*

*(iii) if  $|x| = \max_{i=1,\dots,n} |x_i|$  and  $X_A, X_B$  are independent, then  $h_{2,\epsilon}(\mathcal{P}_{A \cup B}) = h_{2,\epsilon}(\mathcal{P}_A) + h_{2,\epsilon}(\mathcal{P}_B)$ ;*

*(iv)  $\frac{1}{2}h_{2,\epsilon}(\mathcal{P}) \leq h_{3,\epsilon}(\mathcal{P}) \leq h_{2,\epsilon}(\mathcal{P})$ ;*

*(v) for every continuous distribution with compact domain  $D$  and continuous and bounded density function  $p(x)$  and the uniform distribution  $\mathcal{U}$  on  $D$ ,*

$$h_{2,\epsilon}(\mathcal{P}) \leq h_{2,\epsilon}(\mathcal{U}) + o(1) \text{ as } \epsilon \rightarrow 0.$$

**Discrete** case,  $X, Y, Z$  are  $\mathcal{P}$ -iid,  $\epsilon = 0$ ,  $\mathcal{P} = \{p(\mathbf{k}) = P(X = \mathbf{k})\}$ ,

$$h_2(\mathcal{P}) = -\log_2 P(X = Y) = -\log_2 \left( \sum_{\mathbf{k}} p(\mathbf{k})^2 \right) = -\log_2 \mathbf{E}p(X),$$

$$\begin{aligned} h_3(\mathcal{P}) &= -\log_2 P(X = Y, X = Z) = -1/2 \log_2 \left( \sum_{\mathbf{k}} p(\mathbf{k})^3 \right) \\ &= -\log_2 \mathbf{E}p(X)^2 \end{aligned}$$

**Proposition.** *Let  $X = (X_A, X_B)$  be a random  $\mathcal{P}$ -vector.*

(i)  $h_2(\mathcal{P}_A) \leq h_2(\mathcal{P}_{A \cup B});$

(ii) *If  $X_A, X_B$  are independent, then  $h_2(\mathcal{P}_{A \cup B}) = h_2(\mathcal{P}_A) + h_2(\mathcal{P}_B);$*

(iii) *For every discrete non-uniform distributions with finite domains,*  
 $h_2(\mathcal{P}_A) < h_2(\mathcal{U}_A);$

(iv)  $\frac{3}{4} h_2(\mathcal{P}_A) < h_3(\mathcal{P}_A) \leq h_2(\mathcal{P}_A)$  *with the equality iff  $\mathcal{P}$  is uniform.*

**Continuous** case,  $\epsilon > 0$ , density function  $p(x)$ , the volume of  $B_\epsilon(x)$  in  $\mathbb{R}^n$ ,  $b_\epsilon(n) := |B_\epsilon(x)|$

**Proposition.** *Let  $p(x), x \in D$  bounded and continuous or have a finite number of discontinuity points. Then*

$$\begin{aligned} h_\epsilon(\mathcal{P}) &= -\log_2 b_\epsilon(n) - \log_2 \int_D p(x)^2 dx + o(1) \\ &= n \log_2 \frac{1}{\epsilon} - \log_2 b_1(n) - \log_2 \int_D p(x)^2 dx + o(1) \text{ as } \epsilon \rightarrow 0. \end{aligned}$$

If the **differential entropy**  $H_s(\mathcal{P}_A) := \frac{1}{1-s} \log_2 \int_{\mathbb{R}^n} p(x)^s dx$ ,  $s \neq 1$ ,

$$h_{s,\epsilon}(\mathcal{P}_A) = n \log_2 \frac{1}{\epsilon} + \log_2 b_1(n) + H_s(\mathcal{P}_A) + o(1) \text{ as } \epsilon \rightarrow 0,$$



## Examples

**Uniform** random database. Let  $H(A) := \sum_{i \in A} \log_2 |D_i|$  (*information function of  $A$* ),  $r = |A|$ ,

*Discrete* ( $\epsilon=0$ )

$p(\mathbf{k}(A)) = 2^{-H(A)}$ , Rényi entropy  $a = h(\mathcal{P}_A) = H(A)$

*Continuous*  $p(x(A)) = 2^{-H(A)}$ ,  $d_{\min} = \min |D_i|$ ;

$$h_\epsilon(\mathcal{P}_A) = r \log_2 \frac{1}{2\epsilon} + H(A) + \mathbf{O}(r\epsilon^2/d_{\min});$$

**Bernoulli** database:

*Discrete* ( $\epsilon=0$ )

$p(\mathbf{k}(A)) = \prod_{i \in A} \mathcal{Q}(\{k(i)\})$ , Rényi entropy  $h(\mathcal{P}_A) = rh(Q)$ ;

## Continuous

$p(x(A)) = \prod_{i \in A} q(x_i)$ , Rényi entropy (*max*-norm, for  $q(x)$ )  $h_\epsilon(\mathcal{P}_A) = r h_\epsilon(Q)$  and  $h_\epsilon(Q) = \log_2 \frac{1}{2\epsilon} + H(Q) + o(1)$ ;

## Gaussian database:

Tuples  $t_i(A)$  are iid Gaussian  $N(\mu, \Sigma)$  random vectors;  $\lambda_i$  are eigenvalues of  $\Sigma$ ; Rényi entropy (*max*-norm)

$$h_\epsilon(\mathcal{P}_A) = r \log_2 \frac{1}{2\epsilon} + \frac{1}{2} \sum_i \log_2(2\pi \lambda_i) + \mathbf{O}(r\epsilon^2/\lambda_{\min}),$$

– *Bernoulli* database for Gaussian tuples,  $r = |A|$ :

$$h_\epsilon(\mathcal{P}_A) = r(\log_2 \frac{1}{2\epsilon} + \frac{1}{2} \log_2(2\pi\sigma^2) + \mathbf{O}(\epsilon^2)) \text{ as } \epsilon \rightarrow 0.$$

## Quantization $\epsilon$ -entropy

Let  $X \in D \subseteq \mathfrak{R}^n$  be a continuous random vector and Voronoi partition  $D = \cup_{i=1}^{N_\epsilon} B_\epsilon(x_i)$ ,  $\lambda(B_\epsilon(x_i) \cap B_\epsilon(x_j)) = 0$  and  $1 \leq N_\epsilon \leq \infty$ . For a compact set  $D$ , assume that  $N_\epsilon < \infty$ . Let  $V_\epsilon$ -quantizer  $q(X) = x_i$ , where  $i = \operatorname{argmin}_{j=1, \dots, N_\epsilon} |X - x_j|$  and the entropy  $h_\epsilon^R(X) := -\log_2 \sum_{j=1}^{N_\epsilon} p_\epsilon(x_j)^2$ .

**Theorem.** Let  $p(x), x \in D \subseteq \mathfrak{R}^n$  be a continuous density function, and  $q(X)$  the Voronoi  $V_\epsilon$ -quantizer. Then

(i)  $h_\epsilon^R(X) = -\log_2 b_\epsilon(n) + H(\mathcal{P}) + o(1)$ ;

(ii) for a compact set  $D$ ,

$$h_\epsilon^R(X) \leq \log_2 N_\epsilon \text{ and } h_\epsilon(X) \leq \log_2 N_\epsilon + o(1) \text{ as } \epsilon \rightarrow 0.$$

## Discussion

The assertions can be directly generalized for the case of a separable metric space  $(S, d)$  with Lebesgue measure for an  $\epsilon$ -ball. Independent realizations of these random functions can be archived in a database (e.g., Fourier coefficients of a realization in  $L^2[0, 1]$  space or some finite dimensional realization approximations).

## Example

$\epsilon$ -entropy for a Wiener measure  $\mathcal{W}$ . Let two independent Wiener processes  $W_1(t), W_2(t), t \in [0, 1]$ , be Gaussian random vectors taking values in the Hilbert space  $L^2[0, 1]$ . Then  $X(t) = W_1(t) - W_2(t)$  is also a Wiener process with the covariance function  $K(t, s) = 2 \min(t, s), t, s \in [0, 1]$  and the corresponding small ball probability works

$$P(\|W_1 - W_2\|_{L^2[0,1]} \leq \epsilon) = P\left(\int_0^1 X(t)^2 dt \leq \epsilon^2\right) \sim \frac{4\epsilon}{(2\pi)^{1/2}} \exp\left\{-\frac{1}{4\epsilon^2}\right\},$$
$$h_{2,\epsilon}(\mathcal{W}) = \frac{\epsilon^{-2}}{4} + \log_2 \frac{(2\pi)^{1/2}}{4\epsilon} + o(1) \text{ as } \epsilon \rightarrow 0.$$

If  $B_H$  is a fractional Brownian motion with Hurst constant  $H$  and  $S = L^2[0, 1]$ , then

$$h_{2,\epsilon}(\mathcal{B}_H) \sim C_H \epsilon^{-1/H}, C_H > 0.$$

# Random databases. $\epsilon$ -Test probability

Rényi entropies

$$(A) \ a_\epsilon = a_\epsilon(m) = h_{2,\epsilon}(\mathcal{P}_{m,A_m}) \rightarrow \infty \text{ as } m \rightarrow \infty.$$

A “relative” uncertainty in a distribution  $\mathcal{P}$ .

$$(B) \quad \delta_\epsilon := \delta_\epsilon(\mathcal{P}) := 4 h_{3,\epsilon}(\mathcal{P})/h_{2,\epsilon}(\mathcal{P}) - 3 > 0.$$

(i) (B) is valid e.g. for Uniform and Gaussian databases.

(ii) For a discrete distribution  $\mathcal{P}$ ,  $\epsilon=0$ ,  $0 < \delta(\mathcal{P}) \leq 1$  with the equality only for uniform distribution.

Let the mean number of  $\epsilon$ -close tuples,  $M = m(m - 1)/2$ ,

$$\lambda_\epsilon = \lambda_m(\epsilon, A) := \mathbf{E}N_\epsilon(A) = MP(|t_1(A) - t_2(A)| \leq \epsilon) = M2^{-a_\epsilon}.$$

**Theorem.** *Let  $R_m, m \geq 1$ , be a sequence of random tables and (A), (B) hold.*

(i) *For all  $m \geq 1$  and  $\lambda_\epsilon > 0$ ,*

$$|P\{R_m \models_\epsilon A\} - e^{-\lambda_\epsilon}| \leq d_{TV}(\mathcal{L}(N_{A,\epsilon}), Po(\lambda_\epsilon)) \leq 8 \cdot 2^{-\delta_\epsilon a_\epsilon/2} \lambda_\epsilon^{1/2}.$$

(ii) *Let  $\lambda_0$  be a positive constant. Then*

$$P\{R_m \models_\epsilon A\} \rightarrow \begin{cases} 0, & \text{if } \lambda_{m,\epsilon} \rightarrow \infty, \\ e^{-\lambda_0}, & \text{if } \lambda_{m,\epsilon} \rightarrow \lambda_0, \\ 1, & \text{if } \lambda_{m,\epsilon} \rightarrow 0, \end{cases} \quad \text{as } m \rightarrow \infty.$$

## Discussion

The most likely  $\epsilon$ -test candidates are amongst sets with maximal  $\epsilon$ -entropies. Let  $a_\epsilon(r) \geq 2 \log_2 m + c_m$  and  $c_m \rightarrow +\infty$ . Then

$$P\{R_m \models_\epsilon A\} = 1 - o(1) \text{ as } m \rightarrow \infty.$$

These entropies characterize **typical**  $\epsilon$ -tests in a random database.

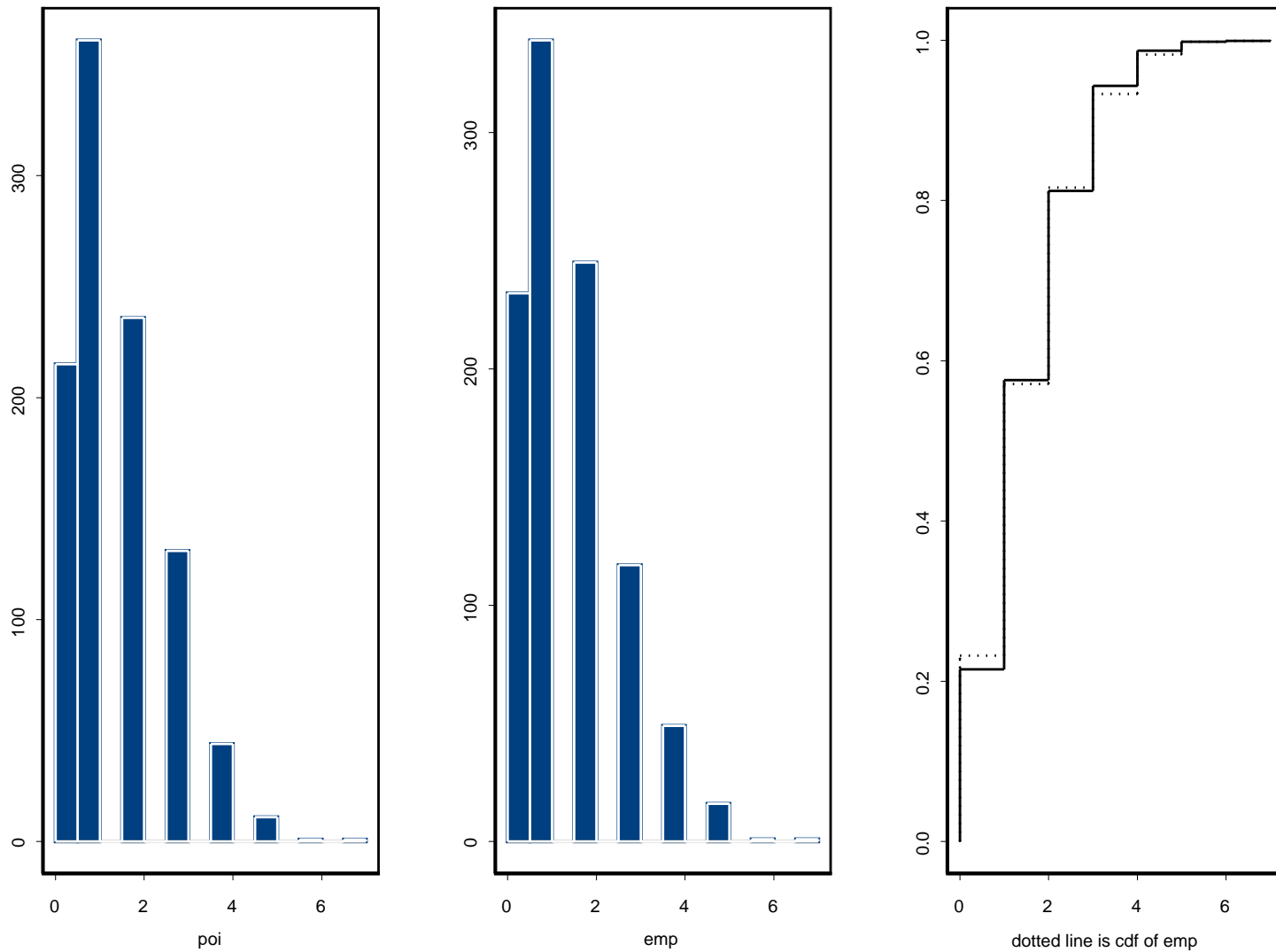
## Sufficient conditions

$$(A) \iff p_{\epsilon, \max} := \max_{x \in D} p_\epsilon(x) \rightarrow 0 \text{ as } m \rightarrow \infty.$$

$$(B) \iff p_{\epsilon, \min} > p_{\epsilon, \max}^2.$$

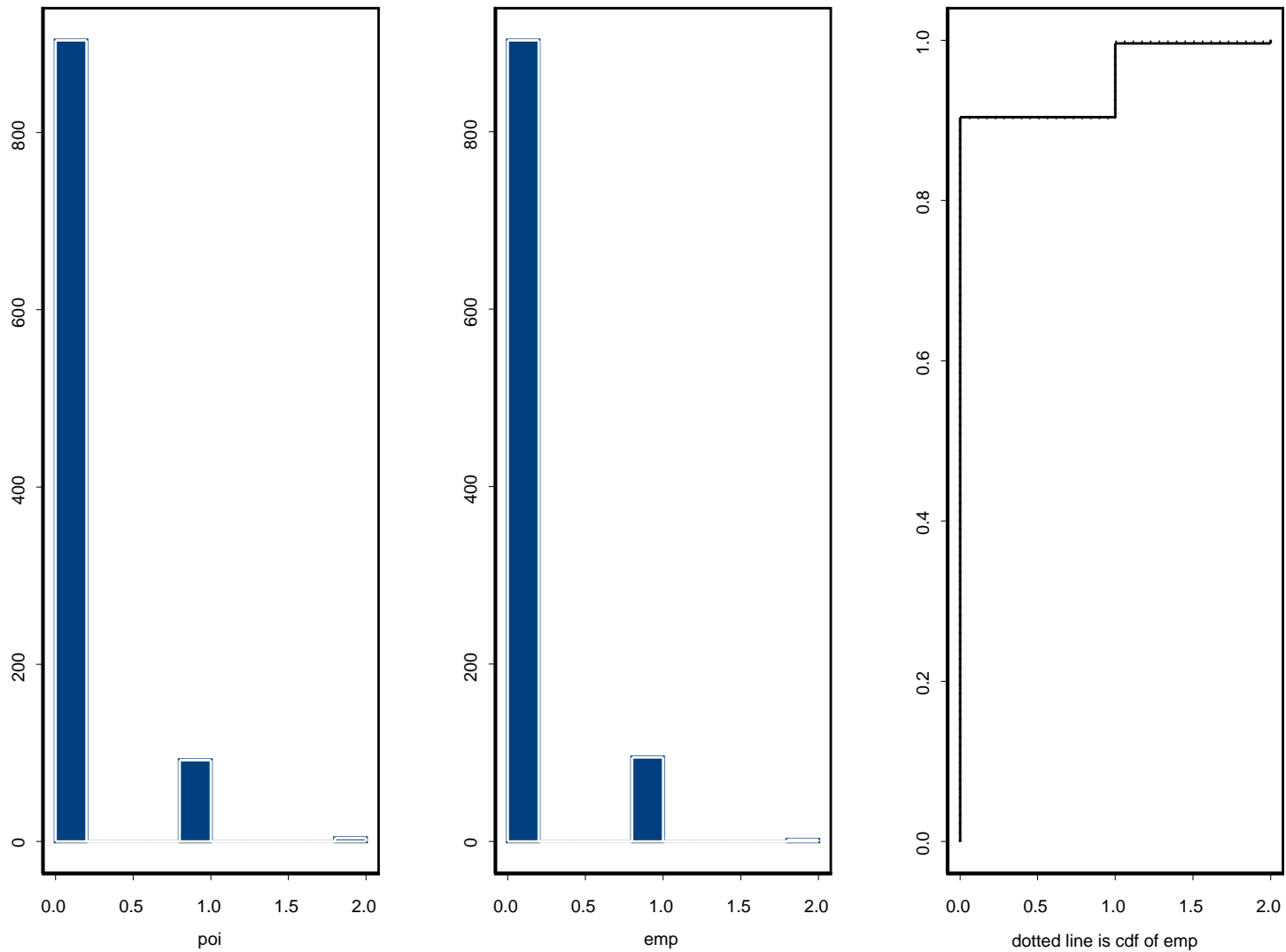
The **test property** for a set of attributes is determined by the  $\epsilon$ -entropy  $h_{2, \epsilon}(\mathcal{P}_{m, A_m})$ .





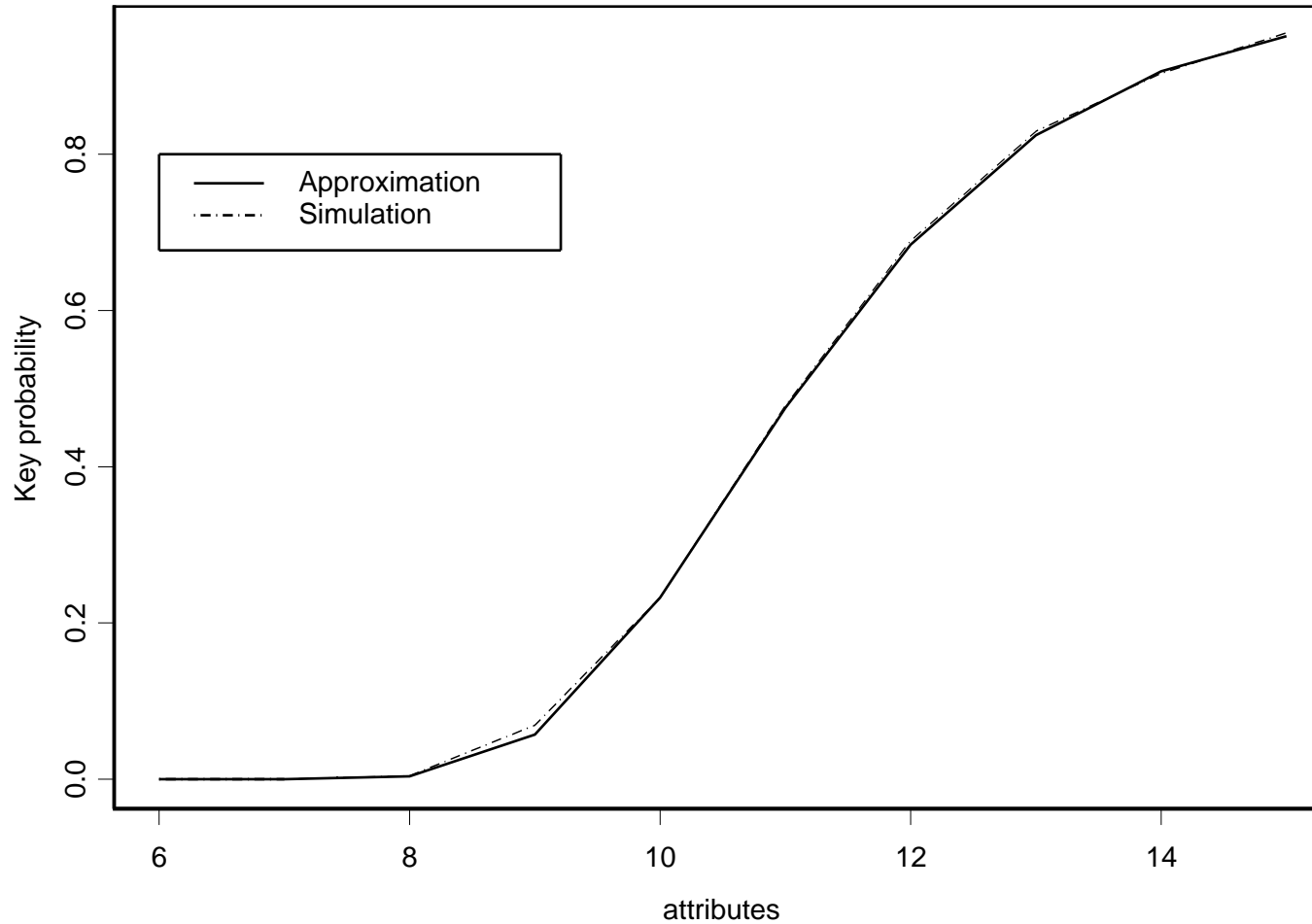
Poisson approximation for standard continuous uniform database, 10 U(0,1)-attributes,  $m = 50, \epsilon = 0.3$ .

Comparison, 14 attributes

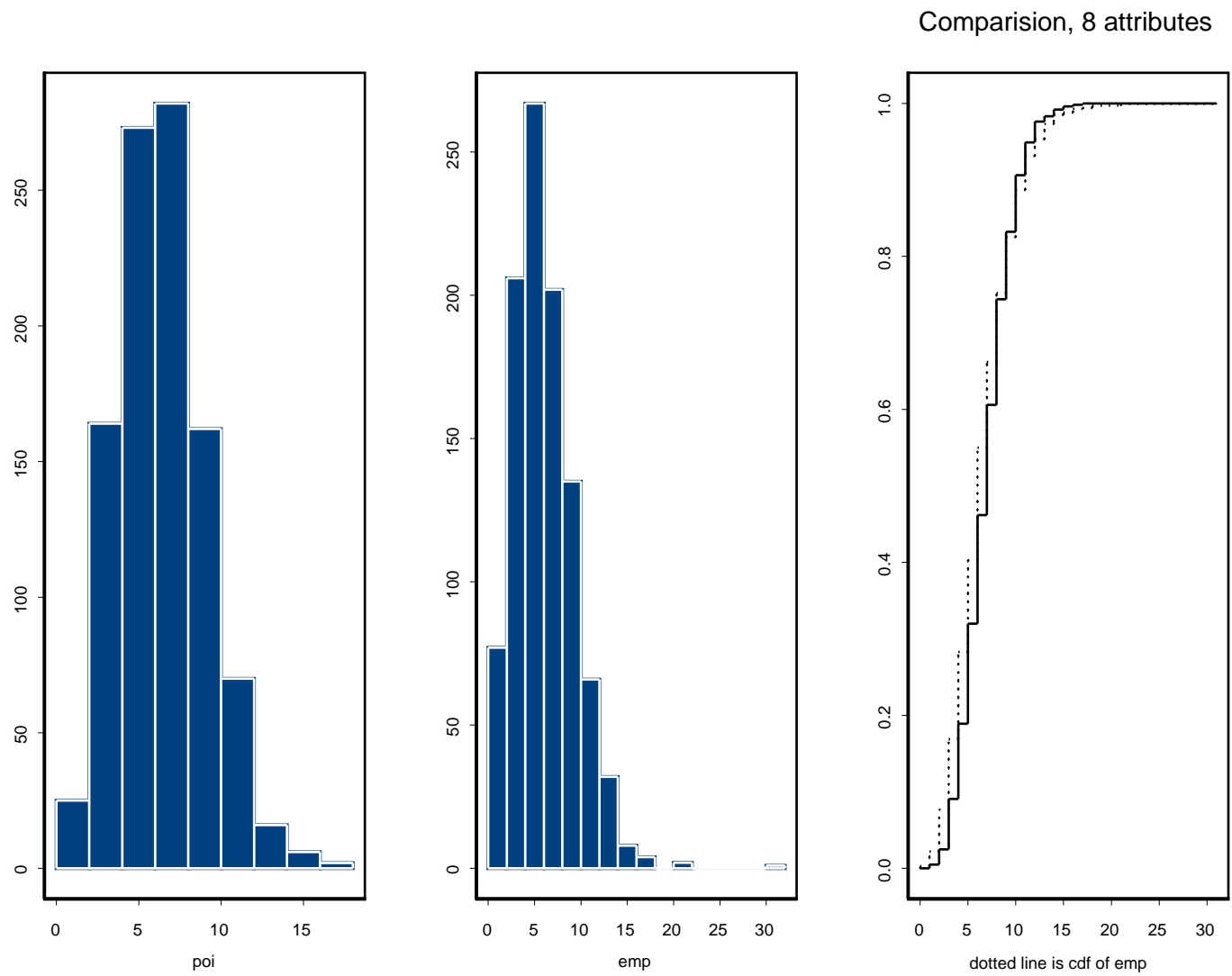


Poisson approximation for standard continuous uniform database, 14 U(0,1)-attributes,  $m = 50, \epsilon = 0.3$ .

## Uniform database

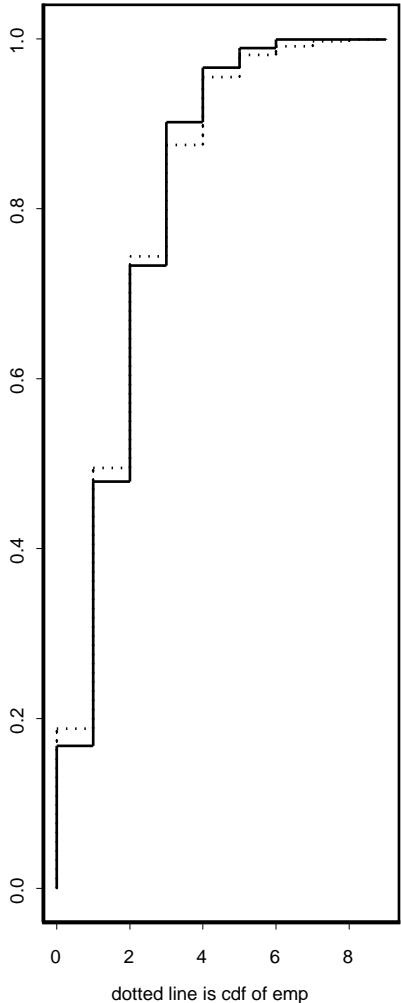
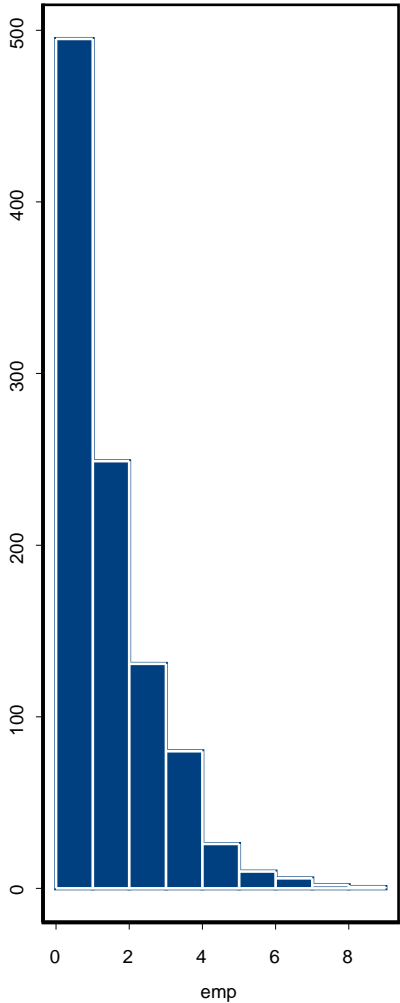
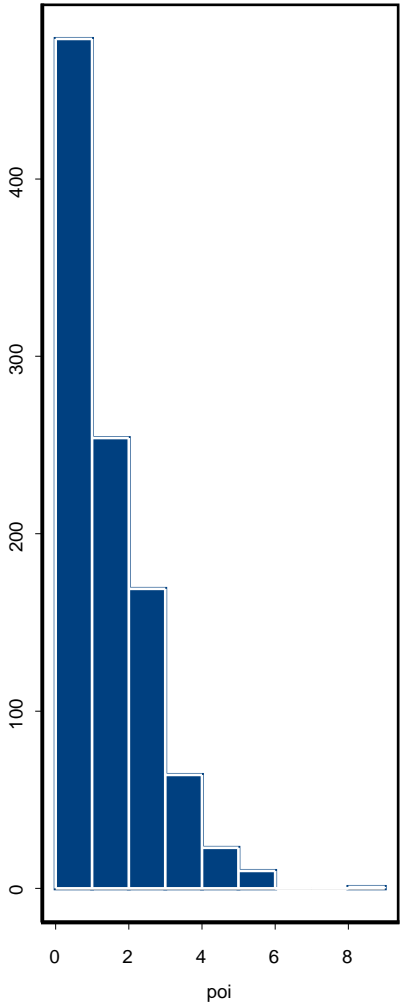


Poisson approximation for standard continuous uniform database,  $U(0,1)$ -attributes,  $m = 50$ ,  $\epsilon = 0.3$ . Empirical distribution (*simulation*),  $N_{sim} = 1000$ .



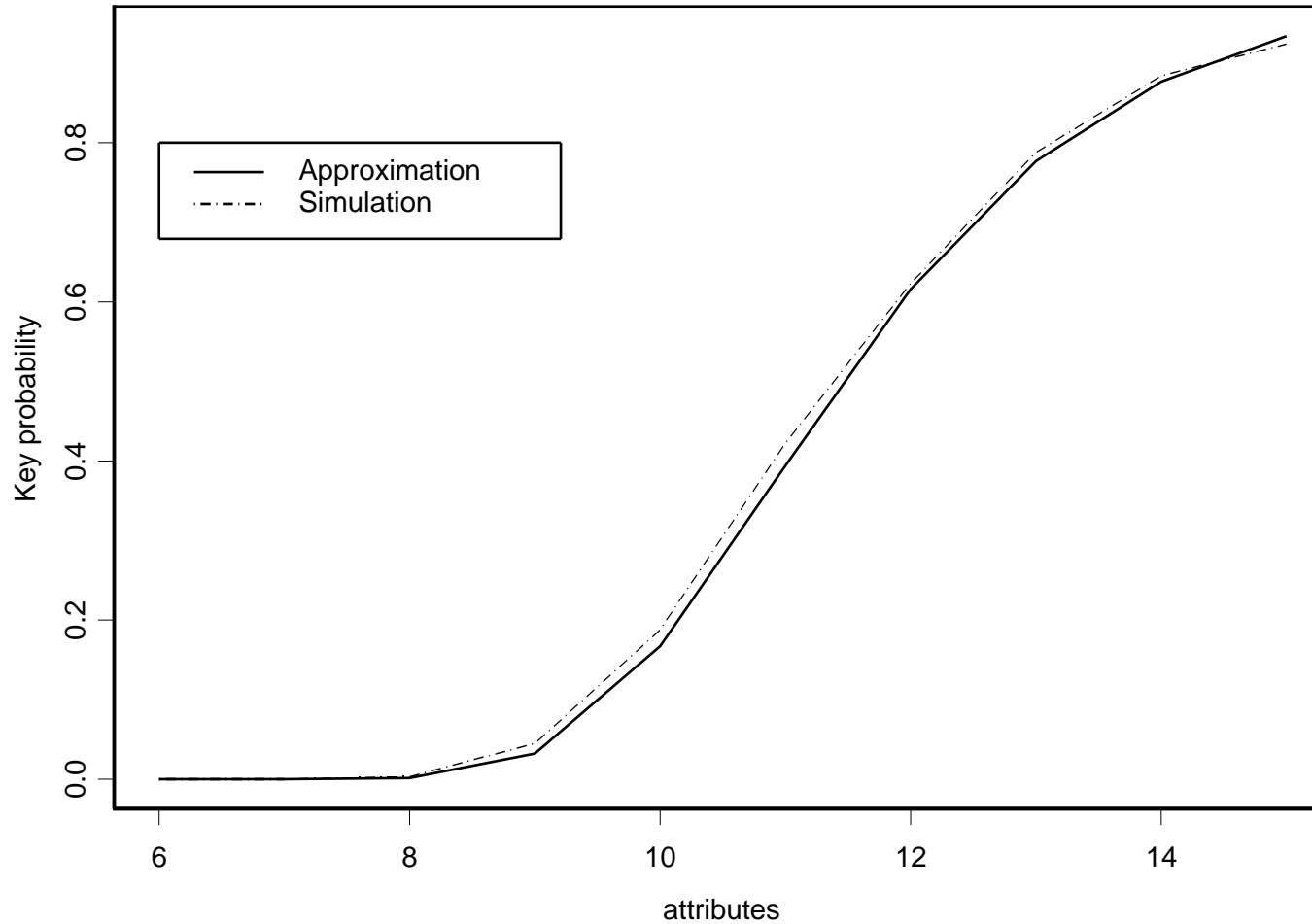
Poisson approximation for standard continuous Gaussian database, 8  $N(0,1)$ -attributes,  $m = 50$ ,  $\epsilon = 1.0$ .

Comparison, 10 attributes



Poisson approximation for standard continuous Gaussian database, 10  $N(0,1)$ -attributes,  $m = 50$ ,  $\epsilon = 1.0$ .

## Gaussian database



Poisson approximation for standard continuous Gaussian database,  $N(0,1)$ -attributes,  $m = 50$ ,  $\epsilon = 1.0$ . Empirical distribution (*simulation*),

$N_{sim} = 1000$ .  
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# Summary

Instead of

**Worst case setting and exhaustive search**

**Stochastic modelling and statistical inference**

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**Thanks!**