



Extrapolation of α -stable random fields

Elena Shmileva

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Interpolation/Extrapolation Problem

Kriging

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Set up

Consider $Y(x), x \in \mathbf{R}^d$ a real-valued random field on \mathbf{R}^d .

Let $\{x_i\}_{i=1}^N, x_i \in \mathbf{R}^d, i = 1..N$ be a set of distinguished locations.

Assume that $\{Y(x_i)\}_{i=1}^N$ are known/ estimated from some given data set.

Problem: to find a linear predictor of Y at arbitrary location $x \in \mathbf{R}^d$, i.e. $Y(x)$. We are looking for this predictor in the following linear form:

$$\hat{Y}(x) = \sum_{i=1}^N \lambda_i(x) Y(x_i), \quad \forall x \in \mathbf{R}^d.$$

Exactness:

$$Y(x_i) = \hat{Y}(x_i), \quad \forall i = 1..N,$$

this hold if and only if

$$\lambda_i(x_i) = 1, \quad \forall i = 1..N, \quad \text{and} \quad \lambda_i(x_j) = 0, \quad \forall i \neq j$$

The problem is to find the set of functions $\{\lambda_i(x), x \in \mathbf{R}^d\}_{i=1}^N$ s.t. the predictor $\{\widehat{Y}(x), x \in \mathbf{R}^d\}$ is "in some sense close" to the random field $\{Y(x), x \in \mathbf{R}^d\}$.

Construction of predictors depends on the properties of the r.f. Y that we have/assume.

If $Y : \mathbf{E}(Y(x))^2 < \infty \rightarrow$ **Kriging**.

Kriging

Master's thesis on Mining Engineering by D.G.Krige, 1951

Mean Square Error minimization:

for each $x \in \mathbf{R}^d$ to find $\lambda = (\lambda_1, \dots, \lambda_N)$ such that

$$\mathbf{E} \left(Y(x) - \sum_{i=1}^N \lambda_i(x) Y(x_i) \right)^2 \rightarrow \min_{\lambda = (\lambda_1, \dots, \lambda_N)} \quad (1)$$

Under conditions:

1. $\mathbf{E}Y(x) = 0$ for all $x \in \mathbf{R}^d$
2. Weak stationarity $Cov(Y(x), Y(s)) = C(\|x - s\|)$, where $\|\cdot\|$ - Euclidian norm in \mathbf{R}^d .

(1) \longleftrightarrow system of N linear equations:

$$\sum_{i=1}^N \lambda_i(x) Cov(Y(x_i), Y(x_j)) = Cov(Y(x), Y(x_j)), j = 1..N$$

Cov. matrix - positive definite, so solution exists and is unique.

Also, $\lambda_i(x_i) = 1, \forall i = 1..N$, and $\lambda_i(x_j) = 0, \forall i \neq j$, so this is interpolation.

Extrapolation of α -stable r. fields, $\alpha \neq 2$

If $\{Y(x_j)\}_{j=1}^N$ is too scattered, $\mathbf{E}(Y(x))^2 = \infty$, then the field Y should have heavy tailed marginals.

What kind of heavy tailed distributions do we know?

X - α -stable, $\alpha \in (0, 2)$.

Properties:

1. $P\{|X| > x\} = C \cdot x^{-\alpha}(1 + o(1))$, as $x \rightarrow \infty$
2. $\mathbf{E}|X|^p < \infty$, $p \in (0, \alpha)$

α -stable r.vector $X = (X_1, \dots, X_N)$ is uniquely determined by $(\Gamma(ds), \mu)$, where $\Gamma(ds)$ is a finite measure on the unite sphere $S^{N-1} \subset \mathbf{R}^N$, $\mu \in \mathbf{R}^N$.

$\Gamma(ds)$ - spectral measure

μ - shift parameter

Characteristic function of r.v. X :

$$\varphi(z) = \exp\left\{-\int_{S^{N-1}} |(z, s)|^\alpha (1 - i \cdot \text{sign}(z, s) \cdot \tan \pi\alpha/2) \Gamma(ds) + i(z, \mu)\right\}$$

for all $z \in \mathbf{R}^N$, $\alpha \neq 1$.

Examples:

1. Let $N = 2$. Consider $X = (X_1, X_2)$
 X_1 independent of $X_2 \iff \Gamma(ds)$ is concentrated on the intersection with the axis
2. X_1 and X_2 linearly dependent $\iff \text{supp}(\Gamma(ds))$ is subset of intersection of S^{N-1} and a hyper-plane
3. $X = (X_1, \dots, X_N)$ is symmetric ($S_\alpha S$) $\iff \Gamma(ds)$ is symmetric and $\mu = 0$

NO covariance and NO correlation coefficient.

How to measure dependence?

Covariation (Samorodnitsky, Taqqu, 1994):

Let (X_1, X_2) be $S_\alpha S$ and $\alpha \in (1, 2)$

$$[X_1, X_2]_\alpha = \int_{S^1} s_1 s_2^{\langle \alpha-1 \rangle} \Gamma(ds),$$

where $a^{\langle p \rangle} := -|a|^p \text{sign}(a)$.

Why this is a good measure of dependence?

Properties of Covariation:

1. X_1, X_2 are independent, then $[X_1, X_2]_\alpha = 0$
2. Let $(X_1, X_2, Y) \text{ S}_\alpha\text{S}$, then
 $[X_1 + X_2, Y]_\alpha = [X_1, Y]_\alpha + [X_2, Y]_\alpha$, but it is not true for the second argument.
3. $[X, Y]_\alpha \neq [Y, X]_\alpha$
4. for $p \in (1, \alpha)$

$$[X, Y]_\alpha = \frac{\sigma_Y^\alpha}{\mathbf{E}|Y|^p} \mathbf{E}XY^{<p-1>},$$

here $\sigma_Y^\alpha = \int_{S^1} |s_2|^\alpha \Gamma(ds)$ scale parameter of Y

So, Covariation is connected with mixed moments, i.e. with dependence structure.

LSL (Least Scale Linear) estimator

What kind of extrapolation methods can we propose?

Let Y be a $S_{\alpha}S$ field. Still $\hat{Y}(x) = \sum_{i=1}^N \lambda_i(x) Y(x_i)$, $\forall x \in \mathbf{R}^d$.

L_p , $p \in (1, \alpha)$ optimization:

$$\mathbf{E} | Y(x) - \sum_{i=1}^N \lambda_i(x) Y(x_i) |^p \rightarrow \min_{\lambda=(\lambda_1, \dots, \lambda_N)} \quad (2)$$

Lemma: $Y(x) - \hat{Y}(x)$ is $S_{\alpha}S$ again.

Lemma: $(\mathbf{E} | Y |^p)^{1/p} = c_{\alpha}(p) \cdot \sigma_Y$

So, (2) \longleftrightarrow

$$\sigma_{Y(x) - \hat{Y}(x)} \rightarrow \min_{\lambda=(\lambda_1, \dots, \lambda_N)}$$

$$\frac{d\sigma_{Y(x)-\hat{Y}(x)}}{d\lambda_i} = \alpha[Y(x_i), Y(x) - \hat{Y}(x)]_\alpha$$

then

$$\left[Y(x_i), Y(x) - \sum_{j=1}^N \lambda_j(x) Y(x_j) \right]_\alpha = 0, \quad i = 1..N \quad (3)$$

no additivity by the second argument, so system of nonlinear equations

If there is an integral representation of Y , then (3) is rewritten via Kernel function and can be solved numerically.

The solution exists and unique.

Exactness is evident.

COL (Covariation Orthogonal Linear) estimator

Let's exchange arguments

$$[Y(x), Y(x_i)]_\alpha - \sum_{j=1}^N \lambda_j(x) [Y(x_j), Y(x_i)]_\alpha = 0, \quad i = 1..N$$

system of N linear equations. Simple to find a solution.
Exactness is evident.

In many cases, for example for Gaussian, sub-Gaussian stable fields, COL and LSL coincide.

MCL (Maximization of Covariation Linear) estimator

$$\text{for each } x \in \mathbf{R}^N \quad [\hat{Y}(x), Y(x)]_\alpha \rightarrow \max_{\lambda=(\lambda_1, \dots, \lambda_N)}$$

Optimization problem with a side condition:

$$\sum_{i=1}^N \lambda_i(x) [Y(x_i), Y(x)]_\alpha \rightarrow \max_{\lambda=(\lambda_1, \dots, \lambda_N)}$$

$$\sigma_{\hat{Y}(x)} = \sigma_{Y(x)}$$

Lagrange function:

$$L(\lambda, \gamma) = \sum_{i=1}^N \lambda_i [Y(x_i), Y(x)]_{\alpha} + \gamma (\sigma_{\hat{Y}(x)} - \sigma_{Y(x)})$$

taking derivatives

$$[Y(x_i), Y(x)]_{\alpha} + \gamma \left[Y(x_i), \sum_{j=1}^N \lambda_j(x) Y(x_j) \right]_{\alpha} = 0$$

Putting $x = x_i$ and $\gamma = -1$, we get exactness.

There is uniqueness under some mild conditions.

Questions

- ▶ How to define $[\cdot, \cdot]_\alpha$ for $\alpha \in (0, 1]$?
- ▶ How to define $[\cdot, \cdot]_\alpha$ for arbitrary α -stable r.v.'s with shift?
- ▶ How to compare all the methods?

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Thank you for your attention!!!