Stability analysis of regenerative queues: recent results

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- Stability analysis of modern queueing systems: a challenging problem;
- main known approaches: fluid approach, Lyapunov functions (for Markovian models);
- we present regenerative stability analysis (see [1]):
 - describe the main steps;
 - give stability conditions for some queueing models;
 - an advantage: can be applied to non-Markovian models.

Definitions

• Consider a stochastic process

$$X = \{X(t), t \in T\}$$
, $T = [0, \infty)$ or $T = \{0, 1, \ldots\}$, state space (R^d, \mathcal{B})

• a path is divided by regeneration points (r.p.'s) β_n onto iid regeneration cycles:

$$G_n := \{ X(t) : \beta_n \le t < \beta_{n+1}; \beta_{n+1} - \beta_n, \}, \ n \ge 0, \ \beta_0 := 0,$$

with the iid cycle periods $\beta_{n+1} - \beta_n$ (in general, $G_0 \neq_{st} G_n$).

• Regeneration measure μ : distribution of $X(\beta_n)$; (for queues often $\mu\{0\} = 1$)

• The renewal process $\{\beta_n\}$ is *positive recurrent* if (β is generic cycle period)

$$\mathsf{E}_{\mu}\beta := \mathsf{E}\beta < \infty \quad (\text{and } \beta_1 < \infty \text{ with probability (w.p.) 1}). \tag{1}$$

• If $E\beta = \infty$ then for each $\beta(0) = x$, the forward renewal time at instant t [9]:

$$\beta(t) := \min\{\beta_k - t : \beta_k - t > 0\} \to \infty \text{ in } P_x \text{-probability}$$



• (1) is crucial for stability because: for a measurable $f: E\{f_0^\beta \mid f(X(t)) \mid dt\} < \infty$:

$$\lim_{T \to \infty} \frac{1}{T} \int_0^T f(X(t)) dt = \frac{\mathsf{E} \int_0^\beta f(X(t)) dt}{\mathsf{E} \beta} (= \mathsf{E} f(X) \text{ if weak limit } X(t) \Rightarrow X \text{ exists}).$$

Main steps of the proof: using predefined conditions we show:

i) negative drift condition: X has negative drift outside bounded set B;

ii) regeneration condition:

$$\inf_{x \in B} \mathsf{P}_x(X \text{ regenerates within a finite interval}) > 0;$$

• i), ii) imply: $\beta(t) \not\rightarrow \infty$ and $\mathsf{E}\beta < \infty$;

An example: Kiefer-Wolfowitz workload (Markov) process in a GI/G/m queue:

$$W_n = (W_n^{(1)}, \dots, W_n^{(m)}), \ n \ge 0,$$

 $\bullet \ W_n^{(i)}$ is the $i {\rm th}$ smallest workload at arrival instant of customer n

• the renewal input with rate λ , service time S; m parallel servers;

i) negative drift condition: $\rho = \lambda ES < m$;

 $ii) \text{ regeneration condition: } \mathsf{P}(\tau > S) := \varepsilon > 0.$

Then for any $W_0 = x \exists$ bounded $B, \varepsilon_1 > 0$ and deterministic $n_i \to \infty$:

$$\inf_{i} \mathsf{P}_x(W_{n_i} \in B) > 0; \tag{2}$$

• \exists constants $T_B = T$:

$$\inf_{x \in B} \mathsf{P}_x(\beta_1 \le T) > 0; \tag{3}$$

• Then (discrete-time) forward regeneration(=renewal) time $\beta(n)$ satisfies

$$\inf_{i} \mathsf{P}_{x}(\beta(n_{i}) \leq T) \geq \inf_{i} \mathsf{P}_{x}(W_{n_{i}} \in B) \inf_{z \in B} \mathsf{P}_{z}(\beta_{1} \leq T) > 0 \quad \Rightarrow \quad \mathsf{E}\beta < \infty.$$

• Using ii) one can show that for \forall bounded B:

$$\nu_x(B) = \mathsf{E}_x(\sum_{k=0}^{\beta-1} I_{W_k \in B}) \le T/\varepsilon,$$

and set B has finite *stationary measure* (mean number of visits B during cycle)

$$\nu(B) = \int \nu_x(B)\mu(dx) < \infty.$$
(4)

• Null recurrence: infinite mean cycle period, $\nu(\mathsf{R}^m_+) = \mathsf{E}_{\mu}\beta = \infty;$

$$\mathsf{P}_x(W_n \in B) \to 0, \text{ as } n \to \infty, \forall B, x.$$
 (5)

Similarly for null recurrent Harris Markov chains [4].

• An advantage: dimension reduction (non-Markovity): the same r.p's

replacement
$$X_n \in R^d$$
 by $Z_n = \sum_{1 \le i \le d} X_n^{(i)}$

A novel approach to prove $\beta_1 < \infty$ under arbitrary X(0); we show:

- the total time X(t) spends in a set B during 1st cycle is finite w.p.1;
- the total time X(t) spends in B is infinite w.p.1 \Rightarrow
- the number of regeneration cycles $\geq 2 \Rightarrow \beta_1 < \infty$.

Recent queueing applications

- Main technique: coupling \Rightarrow monotonicity/dominance
- Classical *m*-server finite retrial system GI/G/m/n with infinite orbit:

renewal input rate λ , interarrival time τ ; service time S; i.i.d. exponential retrial times;

Theorem 1 [2]. Under conditions

 $\lambda \mathsf{E} S < m, \ \mathsf{P}(\tau > S) > 0$

the basic processes (e.g. orbit size N(t)) are positive recurrent.

Underlying idea: as $N(t) \rightarrow \infty$, the idle time of server after each service goes to 0:

Discipline: asymptotically work-conserving.

• Retrial system Σ with constant retrial rate μ_0 and exponential retrial

time (joint work with INRIA, Sophia-Antipolis, France)

renewal input rate λ ; service rate μ ; finite buffer, c servers;

• Motivation: modeling telephone exchange systems [8]; short TCP transfers [6];

ALOHA multiple access protocols [7]: n retrial customers, each has rate μ_0/n .

- To find stability condition, consider an auxiliary loss system $\hat{\Sigma}$:
- an independent Poisson input with rate μ_0 ;
- lost customers joins a virtual orbit $\hat{N}(t)$ with the "output rate" μ_0 (not affecting $\hat{\Sigma}$)
- Σ is less loaded than $\hat{\Sigma} \Rightarrow N(t) \leq_{st} \hat{N}(t) \Rightarrow$
- stability of $\hat{N}(t)$ implies stability of N(t) [5].
- Let \hat{P}_{loss} be the stationary loss probability in $\hat{\Sigma}$ (always exists).

• Theorem ([5]). Under negative drift assumption

input to
$$\hat{N}(t) = \lambda \hat{\mathsf{P}}_{loss} < \mu_0 (1 - \hat{\mathsf{P}}_{loss}) = \mu_0 \hat{\mathsf{P}}_{accept} = output from \ \hat{N}(t), \quad (6)$$

the basic regenerative process $\{N(t)\}$ is positive recurrent.

((6) is stability criteria for M/G/n-type retrial system).

• *Example:* for M/G/1/1-type (Erlang) system condition (6) reads

$$\rho := \frac{\lambda}{\mu} < \frac{\mu_0}{\lambda + \mu_0} \quad \Rightarrow \quad \text{becomes classic: } \rho < 1, \text{ as } \mu_0 \to \infty.$$
 (7)

The proof is based on monotonicity property of loss system [11, 12, 13].

- N-orbit retrial system: input rates λ_i ; retrial rates $\mu_0^{(i)}$; service rates μ_i ;
- necessary stability condition for N = 2:

$$\lambda_i \mathsf{P}_{loss} < (1 - \mathsf{P}_{loss}) \mu_0^{(i)}, \quad i = 1, 2.$$
(8)

 P_{loss} - loss probability in auxiliary loss system with total input rate

$$\lambda_1 + \lambda_2 + \mu_0^{(1)} + \mu_0^{(2)}.$$

• P_{loss} is known for some systems; ((8) is stability criteria for Poisson inputs ?)



Figure 1: N-orbit retrial system with constant retrial rates $\mu_0^{(i)}$

• Discrete queue with m non-reliable servers: input rate λ ; service time S,

server i: interruption rate $\lambda_0^{(i)}$ (non-Poisson), repair time $X^{(i)}$;

• preemptive repeat service interruption: stability condition

$$\lambda \mathsf{E}S + \mathsf{E}S \sum_{i=1}^{m} \lambda_0^{(i)} + \sum_{i=1}^{m} \lambda_0^{(i)} \mathsf{E}X^{(i)} < m \,, \tag{9}$$

lost capacity: interruption+ repeat service= $\sum_{i=1}^{m} \lambda_0^{(i)} \mathsf{E} X^{(i)} + \mathsf{E} S \sum_{i=1}^{m} \lambda_0^{(i)}$;

• preemptive resume service interruption: stability condition

$$\lambda \mathsf{E}S + \sum_{i=1}^{m} \lambda_0^{(i)} \mathsf{E}X^{(i)} < m.$$
(10)

• main idea: construction of common renewal points for the superposition of m indepen-

dent discrete work/repair processes [3].

• *m*-wavelength system with optical fiber lines (*joint with UGENT*):

lengths $a_0 < a_1 < \cdots$, $\lim a_n = \infty$:

renewal input rate λ , interarrival time T; transmission time S;

 $g_n = a_{n+1} - a_n = \text{difference of adjacent lengths};$

$$\Delta^* = \max g_n < \infty;$$

$$\Delta_0 = \limsup_{n \to \infty} g_n = \text{ difference between "longest" lines/orbits}$$

(11)

- buffer control uses a FIFO rule to choose the shortest line with sufficient length \Rightarrow
- a modified Lindley's recursion for waiting time W_k of the kth signal:

$$W_{k+1} = \left[W_k + S_k - T_k \right]_A \tag{12}$$

where $A = \{a_i\}, \ \lceil x \rceil_A = \inf\{y \in A : y \ge x\}$ (to keep FIFO order).

• Classical regenerations for $\{W_k\}$:

$$\beta_0 = 0, \ \beta_{n+1} = \inf(k > \beta_n : W_k = 0), \ n \ge 0.$$

• Theorem ([14, 15, 16]). The workload process is positive recurrent if

$$\lambda \mathsf{E}S + \lambda \Delta_0 < m, \quad equivalently, \tag{13}$$

arrived load + lost capacity (for busy high orbits) < system capacity

- and (regeneration) condition holds: $P(T > \Delta^* + S) > 0$.
- Remark. For iid (or constant) distances $g_n =_{st} \Delta$: inspection paradox makes more

exact stability zone by replacement in (13):

$$\Delta_0 \rightarrow \frac{\mathsf{E}\Delta^2}{2\mathsf{E}\Delta}.$$



Figure 2: A cascade network with two stations

• 2 -station cascade system [17] : stability condition (negative drift)

$$\mu_2 > \lambda_2 + (\lambda_1 - \mu_1)^+, \tag{14}$$

• capacity of 2nd station > input to 2nd station+extra rate from 1st station;



Figure 3: Stability region (coloured area) of a cascade network

• equivalent form of negative drift:

$$\mu_2 - \lambda_2 > 0, \quad \lambda_1 < \mu_2 - \lambda_2 + \mu_1$$

Conclusion

obtained conditions are transparent and close to being stability criteria;

method: applicability to non-Markovian processes;

a wide class *recurrent Harris Markov processes* posses regenerative property [4];

confidence estimation: regenerative simulation based on regenerative CLT [18]:

group data over cycles; apply classic CLT for the new iid enlarged data;

new (macroscopic/cycle) scale: simulation up to an integer number of cycles.

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