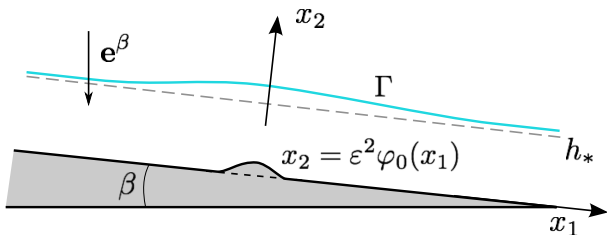


Viscous incompressible free-surface flow down an inclined perturbed plane

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$$\begin{aligned}
 S &= \{x \in \mathbb{R}^2 : x_2 = \varepsilon^2 \varphi_0(x_1)\}, \quad \text{supp} \varphi_0 \subset (-1, 1), \varepsilon > 0, \\
 \Gamma &= \{x \in \mathbb{R}^2 : x_2 = \psi(x_1) = 1 + \varepsilon \Psi(x_1)\}, \\
 \mathbf{e}^\beta &= (\cos \beta, -\sin \beta), \beta \in (0, \frac{\pi}{2})
 \end{aligned}$$

$$\left\{ \begin{array}{l} -\nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla p = -g \mathbf{e}^\beta \quad \text{in } \Omega, \\ \operatorname{div} \mathbf{u} = 0 \quad \text{in } \Omega, \\ \mathbf{u} = 0 \quad \text{on } S, \\ \mathbf{u} \cdot \mathbf{n} = 0, \quad \boldsymbol{\tau} \cdot \mathcal{S}(\mathbf{u}) \mathbf{n} = 0 \quad \text{on } \Gamma, \\ \left(\frac{\psi'(x_1)}{\sqrt{1 + \psi'(x_1)^2}} \right)' = \sigma^{-1} (-p(x) + \mathbf{n} \cdot \mathcal{S}(\mathbf{u}) \mathbf{n})|_{\Gamma}, \\ \lim_{|x_1| \rightarrow \infty} \psi(x_1) = 1, \\ \int_{\sigma_t} u_1(x) dx_2 = \frac{g \sin \alpha}{3\nu}, \end{array} \right.$$

\mathbf{u} – velocity of the fluid, p - pressure, $\alpha = \frac{\pi}{2} - \beta$, $\boldsymbol{\tau}$ and \mathbf{n} are unit vectors of the tangent and the outward normal to the free boundary Γ , $\nu > 0$ and $\sigma > 0$ are the coefficients of viscosity and surface tension, g - acceleration of the gravity, $\mathcal{S}(\mathbf{u})$ is the deformation tensor, σ_t is the cross-section of the domain Ω by the line $x_1 = t$.

V.V. Pukhnachev scheme. Systems of equations are divided in two problems: NS problem in fixed domain

$$\left\{ \begin{array}{l} -\nu \Delta \mathbf{u}_k + (\mathbf{u}_k \cdot \nabla) \mathbf{u}_k + \nabla p_k = -g \mathbf{e}^\beta \quad \text{in } \Omega_k, \\ \operatorname{div} \mathbf{u}_k = 0 \quad \text{in } \Omega_k, \\ \mathbf{u}_k = 0 \quad \text{on } S, \\ \mathbf{u}_k \cdot \mathbf{n} = 0, \quad \boldsymbol{\tau} \cdot \mathcal{S}(\mathbf{u}_k) \mathbf{n} = 0 \quad \text{on } \Gamma_k, \\ \int_{\sigma_t} u_{k1}(x) dx_2 = \frac{g \sin \alpha}{3\nu}, \end{array} \right.$$

and the problem of finding the free boundaries Γ from the equations

$$K_{k+1}(x) = \sigma^{-1}(-p_k(x) + \mathbf{n} \cdot \mathcal{S}(\mathbf{u}_k) \mathbf{n})|_{\Gamma_j}$$

$$\Gamma_0 \Rightarrow \Omega_0 \Rightarrow (\mathbf{u}_0, p_0) \Rightarrow \Gamma_1 \Rightarrow \Omega_1 \Rightarrow (\mathbf{u}_1, p_1) \Rightarrow \dots$$

$$\dots \Gamma_k \Rightarrow \Omega_k \Rightarrow (\mathbf{u}_k, p_k) \Rightarrow \dots$$

Finding the free boundary Γ_{k+1} we have to solve the boundary value problem for the linear ordinary differential equation

$$\left\{ \begin{array}{l} \Psi''_{k+1}(x_1) - g\sigma^{-1} \cos \alpha \Psi_{k+1}(x_1) = \\ = \sigma^{-1} \left(-q_k(x) + \mathbf{n} \cdot \mathcal{S}(\mathbf{u}_k) \mathbf{n} \right) \Big|_{\Gamma_k} + \dots \equiv \Phi_{k+1}(x_1) \\ \lim_{|x_1| \rightarrow \infty} \Psi_{k+1}(x_1) = 0. \end{array} \right.$$

The pressure $q_k(x)$ tends to the constant q_k^+ and q_k^- as $x_1 \rightarrow +\infty$ and $x_1 \rightarrow -\infty$. Since the pressure is defined up to an additive constant we always may normalize $q_k(x)$ so that $q_k^+ = 0$. However, the pressure drop $q_{*k} = q_k^+ - q_k^-$ is the functional on the right-hand sides of the the Stokes problem and, in general, could be nonzero

$$q_{*k} = q_k^+ - q_k^- \neq 0.$$

A unique solution $\Psi_{k+1}(x_1)$ exists if and only if the right-hand side Φ_{k+1} vanishes as $x_1 \rightarrow \pm\infty$. However, this is possible only if $q_{*k} = 0$.

New scheme: (Abergel, Bona, 1992 & Nazarov, K.P., 1993)

Transformation of the flow domain Ω to the unperturbed "uniform" domain $\Omega_0 = \{x \in \mathbb{R}^2 : 0 < x_2 < 1\}$ and linearization of the problem on an appropriate exact solution in Ω_0 .

On each step of iterations the determination of the velocity vector \mathbf{u} and the pressure function p is not separated from the determination of the free boundary Γ (i.e. from the determination of the functions Ψ describing Γ) and all problems are solved in the same fixed domain Ω_0 .

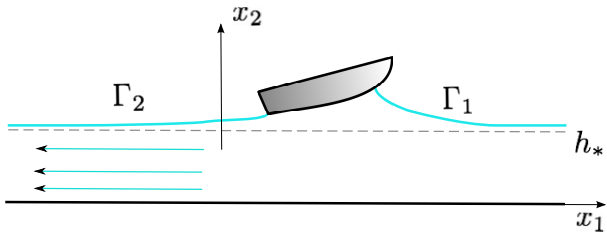
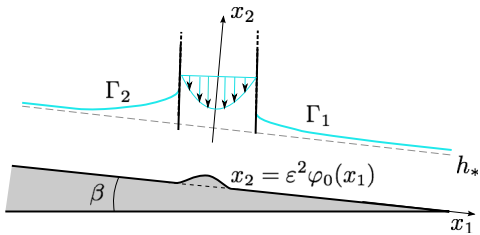
$$(\mathbf{u}_0, p_0, \Psi_0) \Rightarrow (\mathbf{u}_1, p_1, \Psi_1) \Rightarrow \dots \Rightarrow (\mathbf{u}_k, p_k, \Psi_k) \Rightarrow \dots$$

Linearised FVB problem

$$\left\{ \begin{array}{l} -\nu \Delta \mathbf{v} + \nabla q = -(\mathbf{v}^0 \cdot \nabla) \mathbf{v} - (\mathbf{v} \cdot \nabla) \mathbf{v}^0 + \mathbf{F}(\mathbf{v}, q, \Psi) \quad \text{in } \Omega_0, \\ \operatorname{div} \mathbf{v} = 0 \quad \text{in } \Omega_0, \\ v_1|_{y_2=0} = A_1, \quad v_2|_{y_2=0} = A_2 \\ v_2|_{y_2=1} = \frac{g \sin \alpha}{2\nu} \Psi' + B(\Psi), \\ \nu \left(\frac{\partial v_1}{\partial y_2} + \frac{\partial v_2}{\partial y_1} \right) \Big|_{y_2=1} = g \sin \alpha \Psi + D(\mathbf{v}, \Psi), \\ \Psi'' - g \sigma^{-1} \cos \alpha \Psi = \sigma^{-1} \left(-q(y) + 2\nu \frac{\partial v_2}{\partial y_2} \right) \Big|_{y_2=1} + \Phi(\mathbf{v}, \Psi), \\ \lim_{|y_1| \rightarrow \infty} \Psi(y_1) = 0. \end{array} \right.$$

Difficulties: linearized problems contain more boundary conditions as it is allowed by usual ADN-elliptic theory and contains additionally the unknown functions Ψ_k defined on the "free surface" $\{x \in \mathbb{R}^2 : x_2 = 1\}$ of the "uniform" domain Ω_0 . In *Nazarov & K.P.* the proofs are based on L^2 -theory for such generalized elliptic problems¹, and in *Abergel & Bona* – on the detailed investigation of the pseudo-differential operator corresponding to the linearized problem.

¹see Kozlov V.A., Maz'ya V.G., Rossmann J., Elliptic boundary value problems in domains with point singularities, *Math. Surveys and Monographs*, **52**, Amer. Math. Soc., 1997



Modified scheme consists in the following: the unknown flow domain is mapped onto Ω_0 and consider the problem in the fixed domain. However, now we separate the finding of the solutions (\mathbf{v}_k, q_k) of the Stokes problem from the finding of the functions Ψ_k describing the free boundary. In order to insure that on every step of iteration the pressure drop $q_{*k} = 0$, we introduce a smooth function $H_0(x_1)$ and we look for Ψ_k is the form $\Psi_k(x_1) = \chi_k H_0(x_1) + \Upsilon_k(x_1)$. The constants χ_k are chosen so that the pressure $q_k(x)$ of k -iteration satisfies the condition $q_{*k} = 0$. This gives the possibility to solve the problem for $(k + 1)$ -iteration. Finally, the iterations

$$\left\{ \mathbf{u}_k(x), p_k(x), \psi_k(x_1) \right\}, \quad \psi_k(x_1) = 1 + \varepsilon(\chi_k H_0(x_1) + \Upsilon_k(x_1)),$$

converge to the solution $(\mathbf{u}(x), p(x), \psi(x_1))$.

Transformation of the domain

Let

$$\begin{aligned}\omega(y_1, y_2; \Psi) &= \zeta(y_2) \varepsilon \int_{-1}^1 K(\tau) \varphi_0(y_1 + \tau y_2) d\tau \\ &\quad + (1 - \zeta(y_2)) \int_{-1}^1 K(\tau) \Psi(y_1 + \tau y_2) d\tau,\end{aligned}$$

where $K(\tau)$ is an infinitely smooth function such that

$$\text{supp } K \subset (-1, 1), \quad \int_{-1}^1 K(\tau) d\tau = 1, \quad \int_{-1}^1 \tau K(\tau) d\tau = 0,$$

and ζ is an infinitely smooth cut-off function with $\zeta(y_2) = 1$ for $|y_2| \leq \frac{1}{4}$ and $\zeta(y_2) = 0$ for $|y_2| \geq \frac{1}{2}$.

Define the transformation $X(y)$:

$$x_1 = y_1, \quad x_2 = y_2 + \varepsilon \omega(y; \Psi)$$

which maps $\Omega_0 = \{x \in \mathbb{R}^2 : 0 < x_2 < 1\}$ onto the domain $\Omega = \{x \in \mathbb{R}^2 : \varepsilon^2 \varphi_0(x_1) < x_2 < 1 + \varepsilon \Psi_0(x_1)\}$.

Linearization of FVB problem

$$v_1^0(x) = \frac{g \sin \alpha}{2\nu} x_2(2-x_2), \quad v_2^0(x) = 0, \quad p^0(x) = g \cos \alpha(1-x_2), \quad \psi_0(x_1) = 1$$

be the exact Poiseuille type solution for $\varepsilon = 0$, i.e., in Ω_0 .
Substituting

$$\mathbf{u}(x) = \mathbf{v}^0(x) + \varepsilon \mathbf{V}(x), \quad p(x) = p^0(x) + \varepsilon q(x), \quad \psi(x_1) = 1 + \varepsilon \Psi(x_1),$$

introducing a new vector-field \mathbf{v} with components

$$v_1(y) = V_1(X(y))(1 + \varepsilon \partial_{y_2} \omega(y)), \quad v_2(y) = V_2(X(y)) - \varepsilon V_1(X(y)) \partial_{y_1} \omega(y),$$

and making the change of variables $x = X(y)$, we get the following FBV problem in the strip Ω_0 :

Linearization of FVB problem

$$\left\{ \begin{array}{l} -\nu \Delta \mathbf{v} + \nabla q = -(\mathbf{v}^0 \cdot \nabla) \mathbf{v} - (\mathbf{v} \cdot \nabla) \mathbf{v}^0 + \mathbf{F}(\mathbf{v}, q, \Psi) \quad \text{in } \Omega_0, \\ \operatorname{div} \mathbf{v} = 0 \quad \text{in } \Omega_0, \\ v_1|_{y_2=0} = A_1, \quad v_2|_{y_2=0} = A_2 \\ v_2|_{y_2=1} = \frac{g \sin \alpha}{2\nu} \Psi' + B(\Psi), \\ \nu \left(\frac{\partial v_1}{\partial y_2} + \frac{\partial v_2}{\partial y_1} \right) \Big|_{y_2=1} = g \sin \alpha \Psi + D(\mathbf{v}, \Psi), \\ \Psi'' - g \sigma^{-1} \cos \alpha \Psi = \sigma^{-1} \left(-q(y) + 2\nu \frac{\partial v_2}{\partial y_2} \right) \Big|_{y_2=1} + \Phi(\mathbf{v}, \Psi), \\ \lim_{|y_1| \rightarrow \infty} \Psi(y_1) = 0. \end{array} \right.$$

Stokes problem

Consider in Ω_0 the Stokes problem

$$\left\{ \begin{array}{ll} -\nu \Delta \mathbf{w} + \nabla s = \mathbf{f} & \text{in } \Omega_0, \\ \operatorname{div} \mathbf{w} = 0 & \text{in } \Omega_0, \\ \mathbf{w} = \mathbf{a} & \text{on } S_0, \\ \mathbf{w} \cdot \mathbf{n} = b, \quad \boldsymbol{\tau} \cdot \mathcal{S}(\mathbf{w}) \cdot \mathbf{n} = d & \text{on } \Gamma_0. \end{array} \right.$$

Denote by $C^{l+\delta}(\Omega_0; \beta)$ a Banach space of functions having the finite norm

$$\|v\|_{C^{l+\delta}(\Omega_0; \beta)} = \|\exp(\beta \sqrt{1+x_1^2}) v\|_{C^{l+\delta}(\Omega_0)}.$$

Stokes problem

Theorem 1. Let $\mathbf{f} \in C^\delta(\Omega_0; \beta)$, $\mathbf{a} \in C^{2+\delta}(\mathbb{R}; \beta)$, $b \in C^{2+\delta}(\mathbb{R}; \beta)$, $d \in C^{1+\delta}(\mathbb{R}; \beta)$, where $\beta \in (0, \beta_*)$ with sufficiently small β_* , and the following compatibility condition

$$\int_{\mathbb{R}} b(y_1) dy_1 - \int_{\mathbb{R}} a_2(y_1) dy_1 = 0$$

holds.

(i) There exists a unique solution

$\mathbf{w} \in C^{2+\delta}(\Omega_0; \beta)$, $\nabla s \in C^\delta(\Omega_0; \beta)$ satisfying the estimate

$$\begin{aligned} \|\mathbf{w}\|_{C^{2+\delta}(\Omega_0; \beta)} + \|\nabla s\|_{C^\delta(\Omega_0; \beta)} &\leq c \left(\|\mathbf{f}\|_{C^\delta(\Omega_0; \beta)} + \|\mathbf{a}\|_{C^{2+\delta}(\mathbb{R}; \beta)} \right. \\ &\quad \left. + \|b\|_{C^{2+\delta}(\mathbb{R}; \beta)} + \|d\|_{C^{1+\delta}(\mathbb{R}; \beta)} \right). \end{aligned}$$

Moreover, the pressure function s exponentially tends to certain constant limits s^+ and s^- as $y_1 \rightarrow +\infty$ and $y_1 \rightarrow -\infty$.

Stokes problem

(ii) If $s^+ = s^-$, then the pressure s can be normalized so that

$$\lim_{|y_1| \rightarrow \infty} s(y) = 0 \text{ and}$$

$$\|s\|_{C^{1+\delta}(\Omega_0; \beta)} \leq c \left(\|\mathbf{f}\|_{C^\delta(\Omega_0; \beta)} + \|\mathbf{a}\|_{C^{2+\delta}(\mathbb{R}; \beta)} + \|\mathbf{b}\|_{C^{2+\delta}(\mathbb{R}; \beta)} + \|\mathbf{d}\|_{C^{1+\delta}(\mathbb{R}; \beta)} \right).$$

(iii) The difference $s_* = s^+ - s^-$ is uniquely determined by the data of the Stokes problem:

$$s_* = s^+ - s^- = \int_{\Omega} \mathbf{f} \cdot \mathbf{W}^0 dy + \int_{S_0} (3\nu a_1 - a_2 Q^0) dy_1 + \int_{\Gamma_0} \left(b Q^0 + \frac{3}{2} d \right) dy_1,$$

where $W_1^0(y) = \frac{3y_2(2-y_2)}{2}$, $W_2^0(y) \equiv 0$, $Q^0(y) = -3\nu y_1$ is the Poiseuille solution in Ω_0 satisfying the boundary conditions $W^0(y)|_{y_2=0} = 0$, $W_2^0(y)|_{y_2=1} = 0$ and having the unit flux.

BVP for the ordinary differential equation

Consider the following problem

$$\begin{cases} \Upsilon''(y_1) - \gamma_0 \Upsilon(y_1) = G(y_1), & y_1 \in \mathbb{R}, \\ \lim_{|y_1| \rightarrow \infty} \Upsilon(y_1) = 0, \end{cases}$$

where $\gamma_0 = g\sigma^{-1} \cos \alpha > 0$.

Theorem 2. *Let $G \in C^{1+\delta}(\mathbb{R}; \beta)$, $\beta > 0$. Then there exists a unique solution $\Upsilon \in C^{3+\delta}(\mathbb{R}; \beta)$ and the following estimate*

$$\|\Upsilon\|_{C^{3+\delta}(\mathbb{R}; \beta)} \leq c \|G\|_{C^{1+\delta}(\mathbb{R}; \beta)}$$

holds.

Successive approximations

Let a function $H_0 \in C^{l+3+\delta}(\mathbb{R}; \beta)$ be such that

$$\int_{-\infty}^{\infty} \left(\frac{1}{2\nu} H_0'(y_1) Q^0(y_1) + \frac{3}{2} H_0(y_1) \right) dy_1 = \kappa_0 \neq 0. \quad (1)$$

We chose H_0 as a solution of the problem

$$\begin{cases} H_0''(y_1) - \gamma_0 H_0(y_1) = h_0(y_1), \\ \lim_{|y_1| \rightarrow \infty} H_0(y_1) = 0, \end{cases} \quad (2)$$

where $\gamma_0 = g\sigma^{-1} \cos \alpha$, $h_0 \in C^{l+3+\delta}(\mathbb{R}; \beta)$,

$$\|h_0\|_{C^{l+1+\delta}(\mathbb{R}; \beta)} \leq c\varepsilon \quad \text{and} \quad \int_{\mathbb{R}} h_0(y_1) dy_1 = -1. \quad (3)$$

Relations (3) are possible if there holds the following condition

$$0 < \beta \leq c_0 \varepsilon \leq \beta_*.$$

Successive approximations

Then

$$\|H_0\|_{C^{l+3+\delta}(\mathbb{R};\beta)} \leq c \|h_0\|_{C^{l+1+\delta}(\mathbb{R};\beta)} \leq c\varepsilon.$$

Integrating (2) we get

$$\begin{aligned} -1 &= \int_{\mathbb{R}} h_0(y_1) dy_1 = \int_{\mathbb{R}} (H_0''(y_1) - \gamma_0 H_0(y_1)) dy_1 \\ &= -g\sigma^{-1} \cos \alpha \int_{\mathbb{R}} H_0(y_1) dy_1. \end{aligned}$$

On the other hand, integrating by parts we obtain

$$\kappa_0 = \int_{-\infty}^{\infty} \left(\frac{1}{2\nu} H_0'(y_1) Q^0(y_1) + \frac{3}{2} H_0(y_1) \right) dy_1 = 3 \int_{\mathbb{R}} H_0(y_1) dy_1$$

($Q_0(y_1) = -3\nu y_1$). From this formula we conclude that

$$\kappa_0 = \frac{3\sigma}{g \cos \alpha} \neq 0.$$

Successive approximations

Take $\Psi = \chi_* H_0 + \Upsilon$, where the constant χ_* will be defined later:

$$\left\{ \begin{array}{l} -\nu \Delta \mathbf{v} + \nabla q = -(\mathbf{v}^0 \cdot \nabla) \mathbf{v} - (\mathbf{v} \cdot \nabla) \mathbf{v}^0 + \\ \quad + \mathbf{F}(\mathbf{u}, q, \chi_* H_0 + \Upsilon) \quad \text{in } \Omega_0, \\ \quad \quad \quad \text{div } \mathbf{v} = 0 \quad \text{in } \Omega_0, \\ \quad \quad \quad v_1|_{y_2=0} = A_1, \quad v_2|_{y_2=0} = A_2, \\ v_2|_{y_2=1} = \chi_* \frac{g \sin \alpha}{2\nu} H_0' + \frac{g \sin \alpha}{2\nu} \Upsilon' + B(\chi_* H_0 + \Upsilon), \\ \quad \nu \left(\frac{\partial v_1}{\partial y_2} + \frac{\partial v_2}{\partial y_1} \right) \Big|_{x_2=1} = g \sin \alpha \chi_* H_0 + g \sin \alpha \Upsilon + \\ \quad \quad \quad + D(\mathbf{u}, \chi_* H_0 + \Upsilon), \\ \Upsilon'' - g \sigma^{-1} \cos \alpha \Upsilon = \chi_* (-H_0'' + g \sigma^{-1} \cos \alpha H_0) + \\ \quad + \sigma^{-1} \left(-q(y) + 2\nu \frac{\partial v_2}{\partial y_2} \right) \Big|_{y_2=1} + \Phi(\mathbf{u}, \chi_* H_0 + \Upsilon), \\ \quad \quad \quad \lim_{|y_1| \rightarrow \infty} \Upsilon(y_1) = 0. \end{array} \right.$$

Successive approximations

Take as zero approximation $(\mathbf{u}_0, p_0, \psi_0, \chi_0) = (\mathbf{v}^0, p^0, 1, 0)$. Define

$$\chi_1 = -\frac{1}{g \sin \alpha k_0} \int_{S_0} (3\nu A_1 - A_2 Q^0) dy_1,$$

$\mathbf{u}_1 = \mathbf{v}^0 + \varepsilon \mathbf{v}_1, p_1 = p^0 + \varepsilon q_1$, where

$$\left\{ \begin{array}{l} -\nu \Delta \mathbf{v}_1 + \nabla q_1 = 0 \quad \text{in } \Omega_0, \\ \operatorname{div} \mathbf{v}_1 = 0 \quad \text{in } \Omega_0, \\ \mathbf{v}_1|_{y_2=0} = \mathbf{A} = (A_1, A_2), \\ v_{21}|_{y_2=1} = \chi_1 \frac{g \sin \alpha}{2\nu} H'_0, \\ \nu \left(\frac{\partial v_{11}}{\partial y_2} + \frac{\partial v_{21}}{\partial y_1} \right) \Big|_{y_2=1} = \chi_1 g \sin \alpha H_0; \end{array} \right.$$

and $\psi_1 = 1 + \varepsilon(\chi_1 H_0 + \Upsilon_1)$, where

$$\left\{ \begin{array}{l} \Upsilon_1'' - g\sigma^{-1} \cos \alpha \Upsilon_1 = \chi_1 (-H_0'' + g\sigma^{-1} \cos \alpha H_0) + \\ \quad + \sigma^{-1} \left(-q_1(y) + 2\nu \frac{\partial v_{21}}{\partial y_2} \right) \Big|_{y_2=1} + \Phi(\mathbf{u}_1, \psi_0), \\ \lim_{|y_1| \rightarrow \infty} \Upsilon_1(y_1) = 0. \end{array} \right.$$

Successive approximations

The following approximations are defined by

$$\mathbf{u}_{n+1} = \mathbf{v}^0 + \varepsilon \mathbf{v}_{n+1}, \quad p_{n+1} = p^0 + \varepsilon q_{n+1}, \quad \psi_{n+1} = 1 + \varepsilon (\chi_{n+1} H_0 + \Upsilon_{n+1}),$$

where

$$\begin{aligned} \chi_{n+1} = & -(g \sin \alpha k_0)^{-1} \left[\int_{\Omega_0} (- (\mathbf{v}^0 \cdot \nabla) \mathbf{v}_n - (\mathbf{v}_n \cdot \nabla) \mathbf{v}^0) \cdot \mathbf{W}^0 dy \right. \\ & + \int_{\Omega} \mathbf{F}(\mathbf{u}_n, p_n, \chi_n H_0 + \Upsilon_n) \cdot \mathbf{W}^0 dy + \int_{S_0} (3\nu A_1 - A_2 Q^0) dy_1 \\ & + \int_{\Gamma_0} (B(\chi_n H_0 + \Upsilon_n) Q^0 + \frac{3}{2} D(\mathbf{u}_n, \chi_n H_0 + \Upsilon_n)) dy_1 \\ & \left. + g \sin \alpha \int_{\Gamma_0} (\frac{1}{2\nu} \Upsilon_n' Q^0 + \frac{3}{2} \Upsilon_n) dy_1 \right], \end{aligned}$$

Successive approximations

$(\mathbf{v}_{n+1}, q_{n+1})$ are solutions of the following problems:

$$\left\{ \begin{array}{l} -\nu \Delta \mathbf{v}_{n+1} + \nabla q_{n+1} = -(\mathbf{v}^0 \cdot \nabla) \mathbf{v}_n - (\mathbf{v}_n \cdot \nabla) \mathbf{v}^0 + \\ \quad + \mathbf{F}(\mathbf{u}_n, p_n, \chi_n H_0 + \Upsilon_n) \quad \text{in } \Omega_0, \\ \operatorname{div} \mathbf{v}_{n+1} = 0 \quad \text{in } \Omega_0, \\ \mathbf{v}_{n+1}|_{y_2=0} = \mathbf{A}, \\ v_{2n+1}|_{y_2=1} = \chi_{n+1} \frac{g \sin \alpha}{2\nu} H_0' + \frac{g \sin \alpha}{2\nu} \Upsilon_n' + B(\chi_n H_0 + \Upsilon_n), \\ \nu \left(\frac{\partial v_{1n+1}}{\partial y_2} + \frac{\partial v_{2n+1}}{\partial y_1} \right) \Big|_{y_2=1} = \chi_{n+1} g \sin \alpha H_0 + g \sin \alpha \Upsilon_n + \\ \quad + D(\mathbf{u}_n, \chi_n H_0 + \Upsilon_n). \end{array} \right.$$

Finally, Υ_{n+1} are solutions of

$$\left\{ \begin{array}{l} \Upsilon_{n+1}'' - g\sigma^{-1} \cos \alpha \Upsilon_{n+1} = \chi_{n+1} (-H_0'' + g\sigma^{-1} \cos \alpha H_0) + \\ + \sigma^{-1} \left(-q_{n+1}(y) + 2\nu \frac{\partial v_{2n+1}}{\partial y_2} \right) \Big|_{y_2=1} + \Phi(\mathbf{u}_{n+1}, \chi_n H_0 + \Upsilon_n), \\ \lim_{|y_1| \rightarrow \infty} \Upsilon_{n+1}(y_1) = 0. \end{array} \right.$$

Successive approximations

Notice that χ_{n+1} are chosen so that

$$q_{*n+1} = \lim_{x_1 \rightarrow \infty} q_{n+1}(x) - \lim_{x_1 \rightarrow -\infty} q_{n+1}(x) = 0.$$

Indeed,

$$\begin{aligned} q_{n+1}^+ - q_{n+1}^- &= \int_{\Omega_0} \left(-(\mathbf{v}^0 \cdot \nabla) \mathbf{v}_n - (\mathbf{v}_n \cdot \nabla) \mathbf{v}^0 + \mathbf{F}(\mathbf{u}_n, p_n, \chi_n H_0 + \Upsilon_n) \right) \cdot \mathbf{W}^0 dy \\ &+ \int_{S_0} \left(3\nu A_1 - A_2 Q^0 \right) dy_1 + \int_{\Gamma_0} \left(B(\chi_n H_0 + \Upsilon_n) Q^0 + \frac{3}{2} D(\mathbf{u}_n, \chi_n H_0 + \Upsilon_n) \right) dy_1 \\ &+ \frac{3}{2} \int_{\Gamma_0} (\chi_{n+1} g \sin \alpha H_0 + g \sin \alpha \Upsilon_n + D(\mathbf{u}_n, \chi_n H_0 + \Upsilon_n)) dy_1, \end{aligned}$$

or, equivalently,

Successive approximations

$$\begin{aligned} q_{n+1}^+ - q_{n+1}^- &= \chi_{n+1} g \sin \alpha \kappa_0 + \\ &+ \int_{\Omega_0} \left(-(\mathbf{v}^0 \cdot \nabla) \mathbf{v}_n - (\mathbf{v}_n \cdot \nabla) \mathbf{v}^0 + \mathbf{F}(\mathbf{u}_n, p_n, \chi_n H_0 + \Upsilon_n) \right) \cdot \mathbf{W}^0 dy \\ &+ \int_{S_0} \left(3\nu A_1 - A_2 Q^0 \right) dy_1 + \int_{\Gamma_0} \left(B(\chi_n H_0 + \Upsilon_n) Q^0 + \frac{3}{2} D(\mathbf{u}_n, \chi_n H_0 + \Upsilon_n) \right) dy_1 \\ &+ g \sin \alpha \int_{\Gamma_0} \left(\frac{1}{2\nu} \Upsilon_n' Q^0 + \frac{3}{2} \Upsilon_n \right) dy_1, \end{aligned}$$

Convergence of successive approximations

Assume that

$$\varepsilon |\sin \alpha|^{-1} \ll 1 \text{ as } \varepsilon, \alpha \rightarrow 0.$$

Denote

$$Z_n = \|\mathbf{v}_n\|_{C^{l+2+\delta}(\Omega_0; \beta)} + \|q_n\|_{C^{l+1+\delta}(\Omega_0; \beta)} + \|\Upsilon_n\|_{C^{l+3+\delta}(\mathbb{R}; \beta)} + |\chi_n|.$$

For sufficiently small ε and $|\sin \alpha|$ it follows that

$$Z_{n+1} \leq \varrho(Z_n + Z_{n-1}) + c\varepsilon \|\varphi_0\|_{C^{l+3+\delta}(-1,1)} \quad \text{with } \varrho < \frac{1}{2}.$$

Hence if

$$Z_m \leq c\varepsilon(1 - 2\varrho)^{-1} \|\varphi_0\|_{C^{l+3+\delta}(-1,1)} \equiv A_*, \quad m = n - 1, m = n,$$

then

$$Z_{n+1} \leq A_*.$$

Since $Z_0 = 0$ and Z_1 satisfies this inequality, it holds for all $m \geq 1$.

Convergence of successive approximations

Let us estimate the differences

$$R_n = \|\mathbf{v}_{n+1} - \mathbf{v}_n\|_{C^{l+2+\delta}(\Omega_0;\beta)} + \|q_{n+1} - q_n\|_{C^{l+1+\delta}(\Omega_0;\beta)} \\ + \|\Upsilon_{n+1} - \Upsilon_n\|_{C^{l+3+\delta}(\mathbb{R};\beta)} + |\chi_{n+1} - \chi_n|.$$

For sufficiently small ε and $|\sin \alpha|$ holds the estimate

$$R_n = \|\mathbf{v}_{n+1} - \mathbf{v}_n\|_{C^{l+2+\delta}(\Omega_0;\beta)} + \|q_{n+1} - q_n\|_{C^{l+1+\delta}(\Omega_0;\beta)} \\ + \|\Upsilon_{n+1} - \Upsilon_n\|_{C^{l+3+\delta}(\mathbb{R};\beta)} + |\chi_{n+1} - \chi_n| \\ \leq \varrho \left(\|\mathbf{v}_n - \mathbf{v}_{n-1}\|_{C^{l+2+\delta}(\Omega_0;\beta)} + \|\mathbf{v}_{n-1} - \mathbf{v}_{n-2}\|_{C^{l+2+\delta}(\Omega_0;\beta)} \right. \\ \left. + \|q_n - q_{n-1}\|_{C^{l+1+\delta}(\Omega_0;\beta)} + \|q_{n-1} - q_{n-2}\|_{C^{l+1+\delta}(\Omega_0;\beta)} \right. \\ \left. + \|\Upsilon_n - \Upsilon_{n-1}\|_{C^{l+3+\delta}(\mathbb{R};\beta)} + \|\Upsilon_{n-1} - \Upsilon_{n-2}\|_{C^{l+3+\delta}(\mathbb{R};\beta)} \right. \\ \left. + |\chi_n - \chi_{n-1}| + |\chi_{n-1} - \chi_{n-2}| \right) = \varrho (R_{n-1} + R_{n-2})$$

with $\varrho < \frac{1}{2}$.

Convergence of successive approximations

We have two inequalities

$$R_n \leq 2A_* \quad \text{and} \quad R_n \leq \varrho(R_{n-1} + R_{n-2}) \quad \text{with} \quad \varrho < \frac{1}{2}$$

from which it follows that

$$\begin{aligned} & \| \mathbf{v}_m - \mathbf{v}_n \|_{C^{l+2+\delta}(\Omega_0; \beta)} + \| \mathbf{q}_m - \mathbf{q}_n \|_{C^{l+1+\delta}(\Omega_0; \beta)} \\ & + \| \Upsilon_m - \Upsilon_n \|_{C^{l+3+\delta}(\mathbb{R}; \beta)} + | \chi_m - \chi_n | \rightarrow 0 \quad \text{as} \quad n, m \rightarrow \infty. \end{aligned}$$

Hence the sequence

$$\{ \mathbf{v}_n, \mathbf{q}_n, \Upsilon_n, \chi_n \} \mapsto \{ \mathbf{v}, \mathbf{q}, \Upsilon, \chi_* \}$$

in $C^{l+2+\delta}(\Omega_0; \beta) \times C^{l+1+\delta}(\Omega_0; \beta) \times C^{l+3+\delta}(\mathbb{R}; \beta) \times \mathbb{R}$.

Existence of the solution

Obviously,

$\mathbf{u}(x) = \mathbf{v}^0(x) + \mathbf{v}(x)$, $p(x) = p^0(x) + q(x)$, $\psi(x_1) = 1 + \chi_* H_0(x_1) + \Upsilon(x_1)$
is the solution of problem (FB).

THEOREM. Let $\varphi_0 \in C^{l+3+\delta}(-1, 1)$, $\text{supp } \varphi_0 \subset (-1, 1)$,

$$\varepsilon |\sin \alpha|^{-1} \ll 1 \text{ as } \varepsilon, \alpha \rightarrow 0.$$

Then for sufficiently small ε and $|\alpha|$ problem (FB) has a unique solution (\mathbf{u}, p, ψ) . This solution admits a representation

$\mathbf{u}(x) = \mathbf{v}^0 + \mathbf{v}$, $p(x) = p^0(x) + q(x)$, $\psi(x_1) = 1 + \chi_* H_0(x_1) + \Upsilon(x_1)$,
where

$$v_1^0(x) = \frac{g \sin \alpha}{2\nu} x_2(2 - x_2), \quad v_2^0(x) = 0, \quad p^0(x) = g \cos \alpha(1 - x_2),$$

χ_* is a constant,

$$\mathbf{v} \in C^{l+2+\delta}(\Omega_0; \beta), \quad q \in C^{l+1+\delta}(\Omega_0; \beta), \quad H_0, \Upsilon \in C^{l+3+\delta}(\mathbb{R}; \beta).$$